

Using ODT to Model Flame Propagation in Wildland Fire Fuel Beds

David O. Lignell, Elizabeth Monson

Wildland Fire Workshop—24rd Annual ACERC Conference

February 25-26, 2010

Brigham Young University

Sponsored by: USDA Forest Service Rocky Mountain Research Station



Introduction

- Wildland fire modeling represents an important and highly complex process
 - Wide range of length and timescales.
 - Multi-phase flow in non-uniform configurations.
 - Complex combustion with variable fuel properties.

- Physics-based models
 - PDE's, 3D, "resolved"
 - Complex, Costly
 - Too much information

- Empirical models
 - Cost effective
 - Less flexible

Multi-scale modeling: how to couple and transmit essential information between large and small scales



Flame Spread

- Understanding the rate of flame propagation through fuel beds is of crucial importance in the overall problem.
- Flame spread occurs via heat transfer:
 - Radiative
 - Convective
- Focus on fine fuels:
 - grasses, pine needles, brush, small branches.
- Radiative heating competes with convective cooling
 - Fuel is not heated to ignition by radiation.
- Flame spread requires direct flame bathing.
 - Intermittent
 - Turbulent



Radiation and Flame Bathing



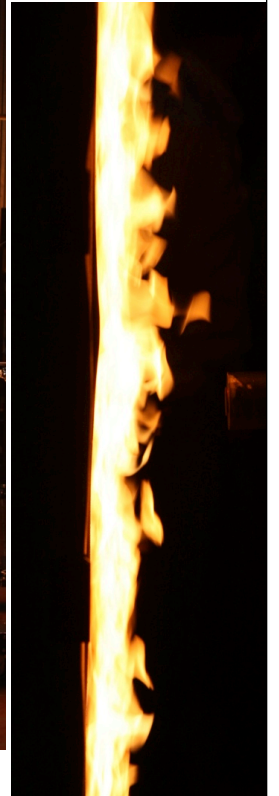
Approach

- Consider lab-scale buoyant fires
 - Pool fires
 - Wall flames
 - Artificial fuel beds with cross flow.
- Predicting the flame spread requires knowledge of the intermittent turbulent flame edge.
 - Flame expansion
 - Fuel product accumulation
 - Fuel spacing
 - Wind speed.



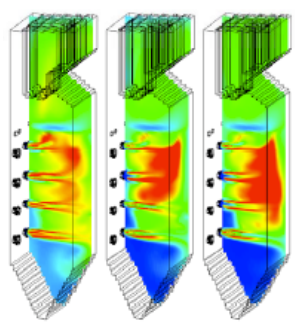
Flame Wall Experiment

- Vertical burner panel
- Ethylene feed $1.75 \text{ L/m}^2\cdot\text{min}$
- Statistically steady
- Examine flame expansion
 - vary fuel flow rate
- Heat flux
- Temperature profile
- Flame intermittency



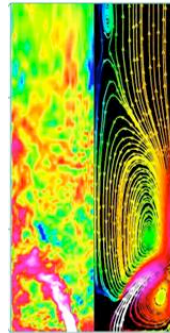
Simulation Approaches

- Three major simulation approaches
- Levels of turbulence modeling
 - **RANS** → inexpensive; but mean only
 - **LES** → expensive; capture large eddies, but miss flame structure
 - **DNS** → cost prohibitive; but full resolution



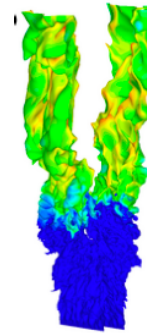
RANS

Engineering
Design,
Optimization



LES

Advanced
Engineering, Research



DNS

Research, Model
Development



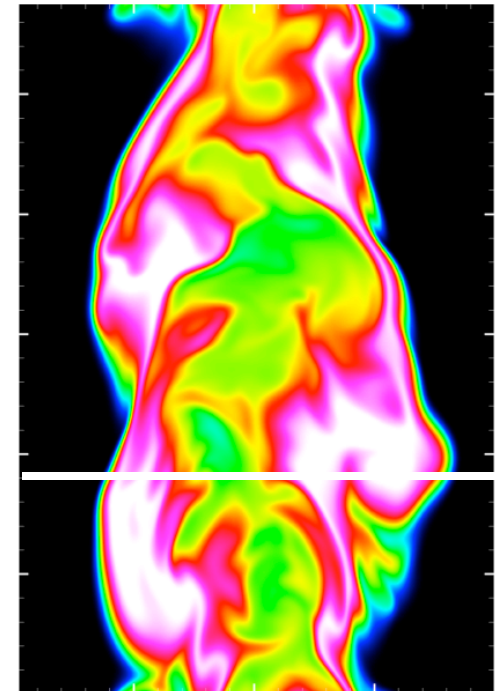
(Subgrid Modeling Required)



Computational Cost

One Dimensional Turbulence (ODT)

- ODT compromise
 - Full resolution of diffusive-reactive flame structure: heat, species, mass, momentum
 - But only 1-D: line of sight through the flame
 - Most flows have a dominant strain direction.
 - Turbulent advection modeled through stochastic “eddy events”
 - Provides structure and statistics of intermittent flame brush.
 - One space direction + an evolution coordinate
 - time \rightarrow temporal ODT
 - space \rightarrow spatial ODT
 - Model is computationally affordable.
 - $O(10)$ min per realization
 - $O(100)$ realizations for statistics



ODT Formulation—Diffusive Advancement

- Evolve reactive-diffusive equations with periodic eddy events.
- Lagrangian control volume formulation.
- Fully adaptive mesh.
- Implicit or explicit detailed chemistry.
- Implied low-Mach assumption.
- Boussinesq buoyant acceleration.
- Line velocities treated as scalars for eddy dynamics
 - 1-D \rightarrow direct cell dilatation

Mass

$$\rho \Delta x = C$$

Species

$$\frac{dY_i}{dt} = -\frac{1}{\rho \Delta x} (j_e - j_w) + \dot{m}_i'''$$

Momentum

$$\frac{du_k}{dt} = -\frac{1}{\rho \Delta x} (\tau_{xk,e} - \tau_{xk,w}) - \frac{1}{\rho} \frac{dP}{dy} \delta_{yk}$$

Energy

$$\frac{dh}{dt} = -\frac{1}{\rho \Delta x} (q_e - q_w) + \frac{1}{\rho} \frac{dP}{dt}$$

$$j_i = -\frac{\rho Y_i D_i}{X_i} \frac{dX_i}{dx}$$

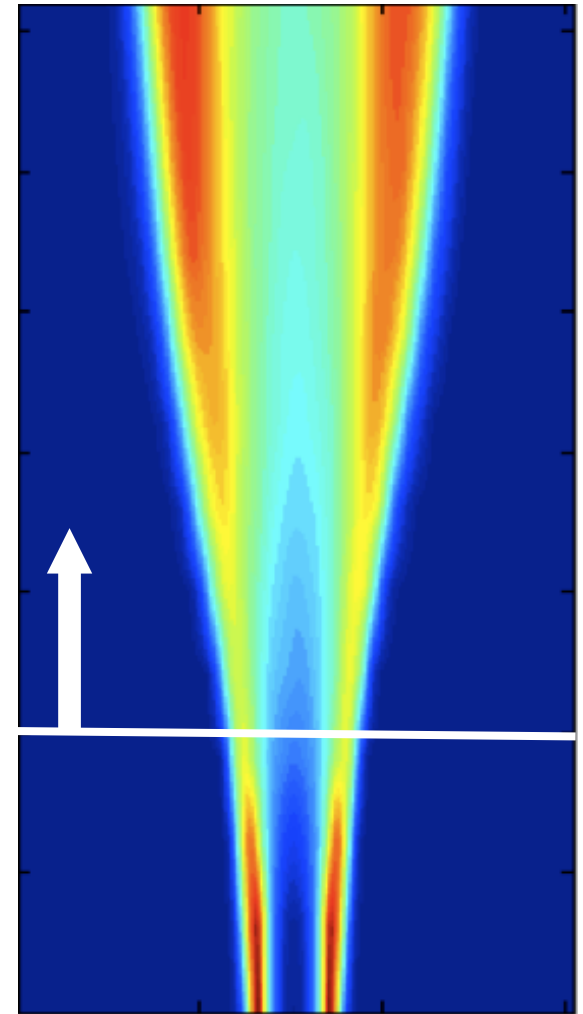
$$\tau_{xk} = -\mu \frac{du_k}{dx}$$

$$q = -\lambda \frac{dT}{dx} + \sum_i h_i j_i$$



Spatial Formulation

- Temporal ODT
 - Advance stationary line in time
 - Channel flow, homogeneous turbulence, temporally-evolving jet, etc.
- Spatial ODT
 - Advance line axially in space under assumed “steady” flow field.
 - Boundary layer approximations applied.
 - A formal analysis shows:
 - $t \rightarrow x$: $(d/dt) = (d/dx)*(dx/dt) = (d/dx)*v$
 - divide through by velocity
 - Cell mass flux, not mass, is conserved



ODT Formulation—Eddy Events

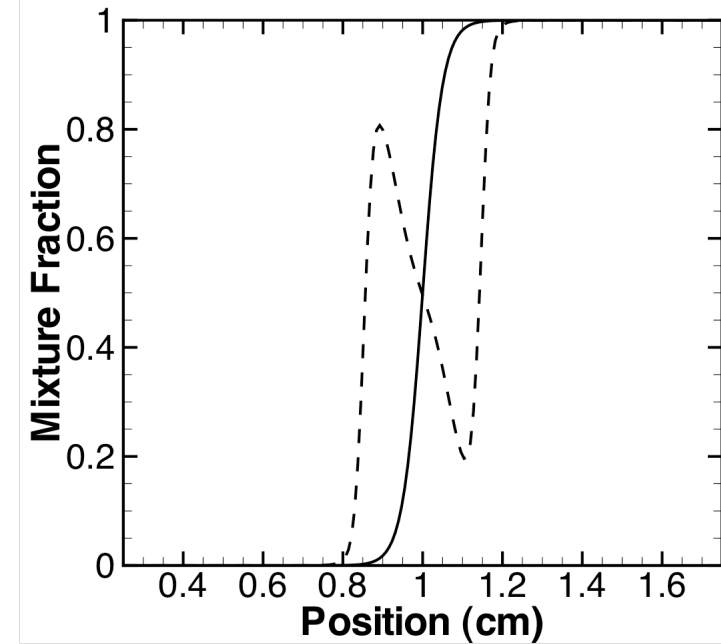
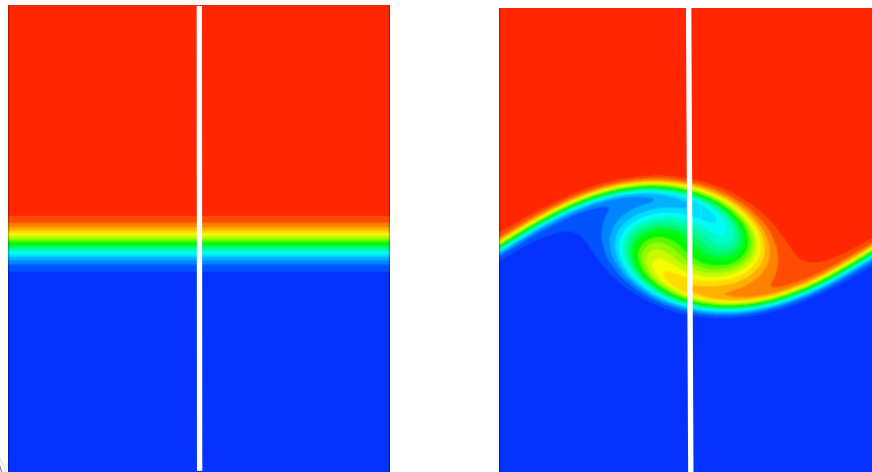
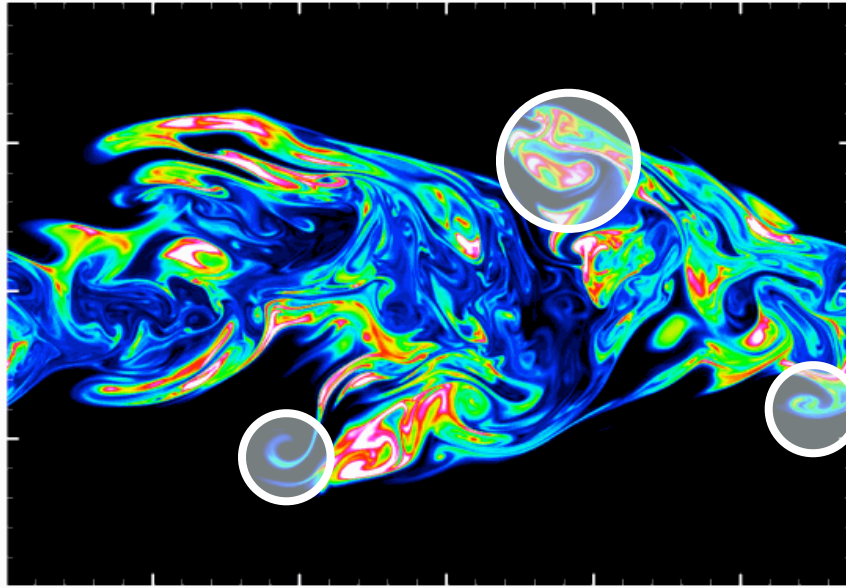
- Turbulent advection modeled via stochastic eddy events.
- Re-map portions of the domain in a manner consistent with turbulent scaling laws.
 - Inertial scaling $E(\kappa) = C\varepsilon^{2/3}\kappa^{-5/3}$ depends on
 - Local energy transfers
 - Non-dissipative energy transfer
 - ε is the only dependent parameter, and $\varepsilon = u^2/\tau$, with $\tau=l/u$
- As turbulence cascades, timescales decrease, strain increases
- The Kelvin-Helmholtz instability is fundamental in turbulence



<http://upload.wikimedia.org/wikipedia/commons/8/8e/KHI.gif>

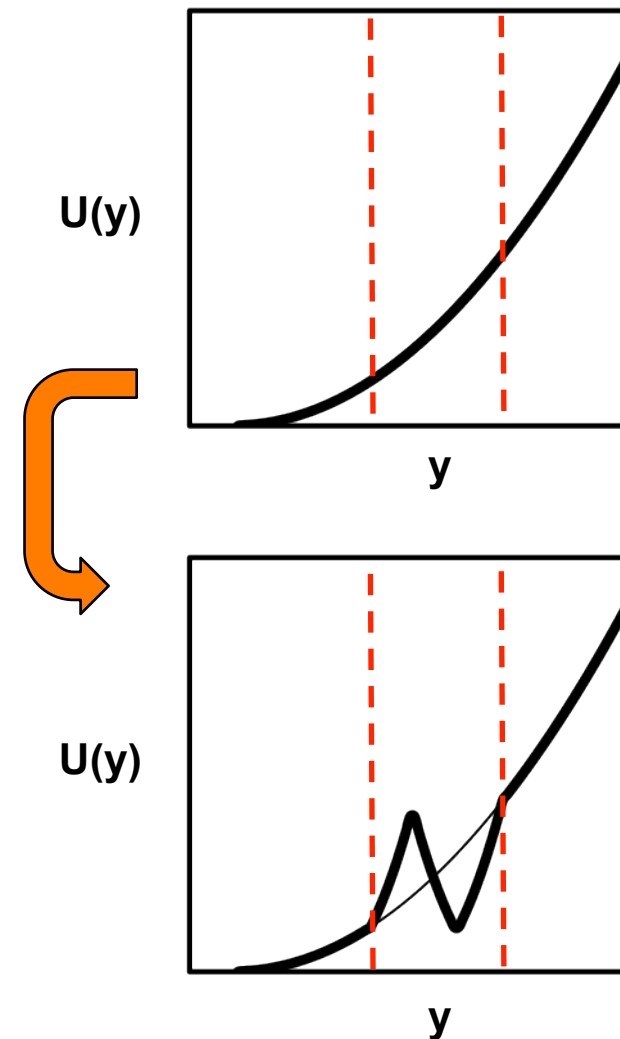
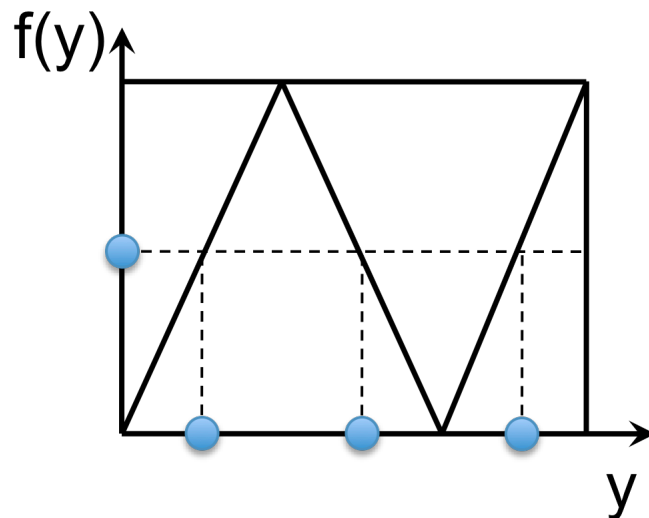


ODT Formulation—Eddy Events



Triplet Map

- Triplet map written in terms of the inverse map
 - Fluid at $f(y)$ is moved to y
- Procedure
 - Make 3 copies of a profile
 - Compress the domains by factor of 3
 - Invert the middle copy.



Eddy Rate Distribution

- Eddy events are consistent with inertial scaling
 - local
 - non-dissipative (u^2 is conserved)
 - consistent timescale: $\tau \sim l/u$
- Determine eddy rate: time, location, size:
 - $\lambda(x_o, l)$ is eddy rate per unit eddy size, per unit domain length
 - Eddies sampled from joint PDF $P(x_o, l) = \lambda/\Lambda$, and accepted with acceptance probability P_a
 - In practice $P(x_o, l)$ is unknown, and the rejection method used
 - E is a measure of the kinetic energy in the eddy and includes a viscous penalty for very small eddies

$$\lambda(x_o, l)$$

$$\Lambda = \iint \lambda(x_o, l) dx_o dl$$

$$P(x_o, l) = \frac{\lambda}{\Lambda}$$

$$\Lambda \Delta t_s = P_a = \frac{\lambda(x_o, l) \Delta t_s}{P(x_o, l)}$$

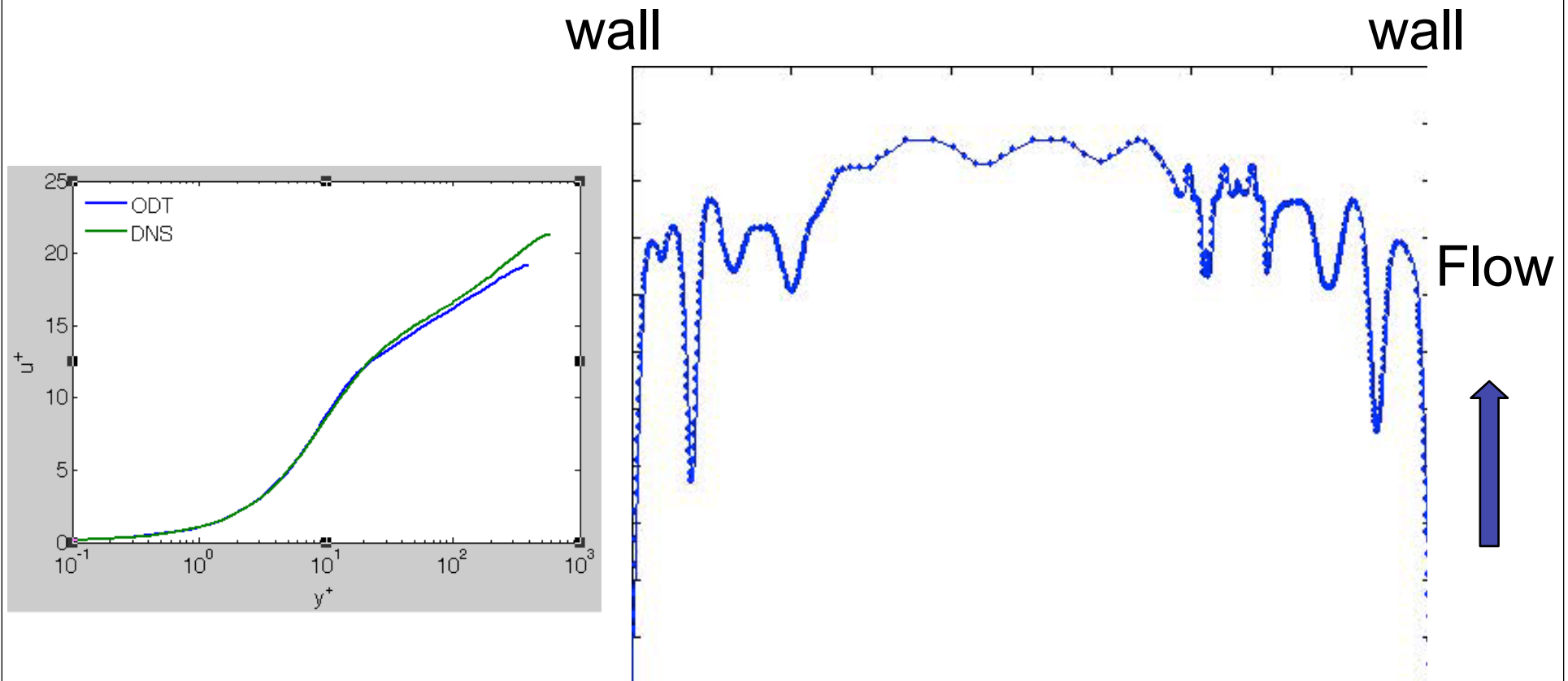
$$\lambda = \frac{1}{l^2 \tau}$$

$$E = \frac{1}{2} \rho l \bar{u}^2 = \frac{1}{2} \rho l^3 / \tau^2$$

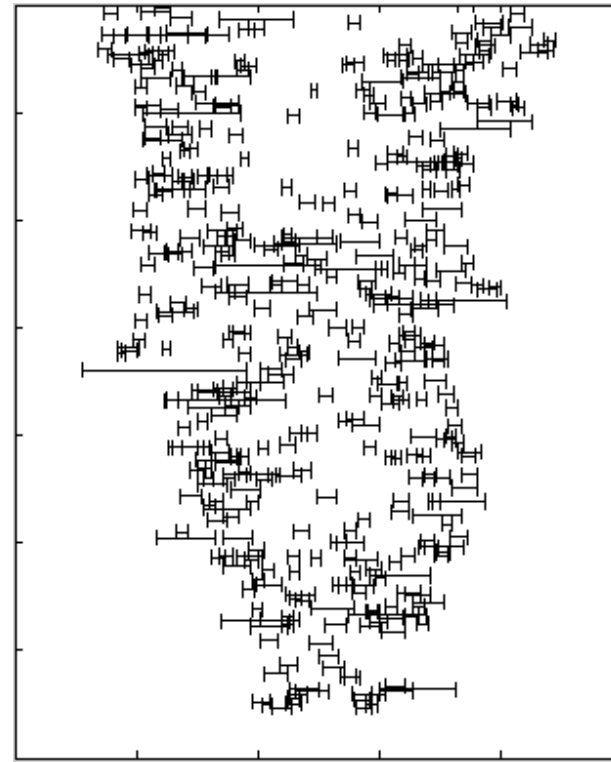
$$\frac{1}{\tau} = C \sqrt{\frac{2E}{\rho l^3}}$$



ODT Validation—Channel Flow



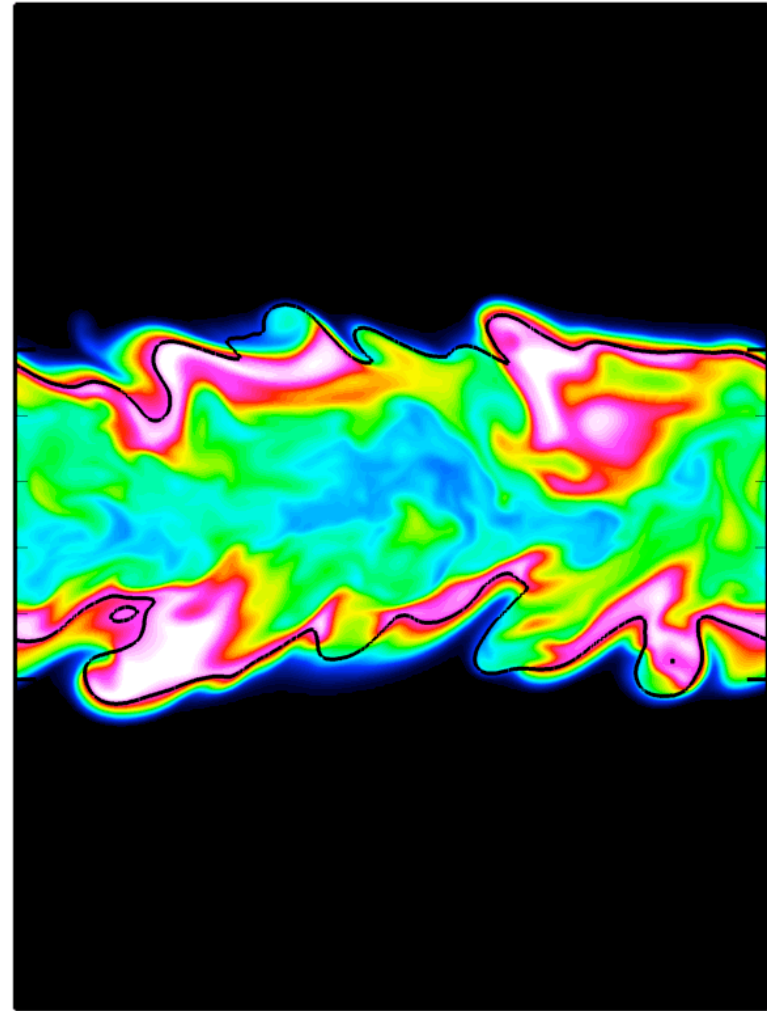
ODT Application—Ethylene Pool Fire



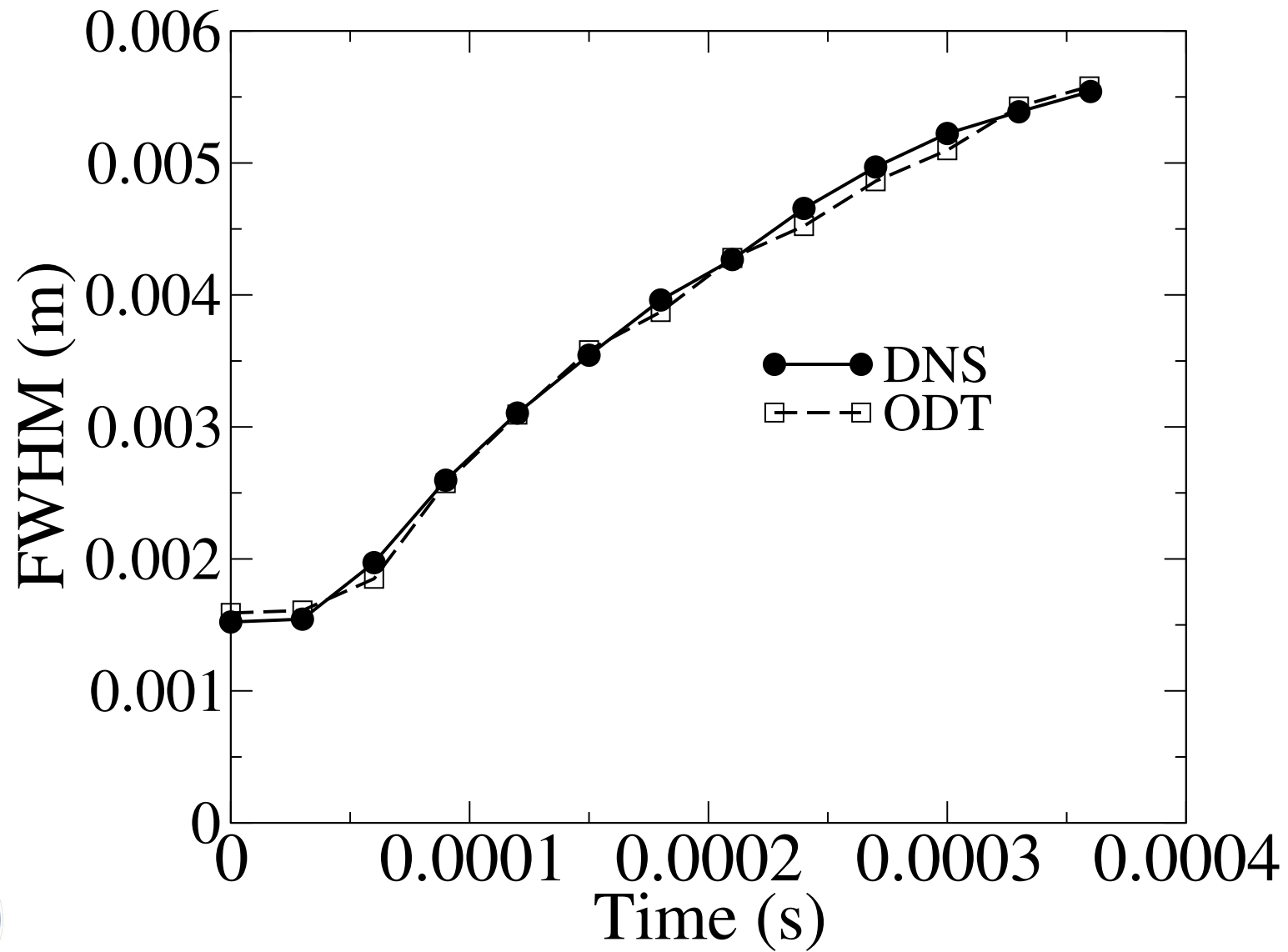
- Buoyant ethylene pool fire
- 5x7 meters
- One realization, run on the order of 100 realizations
 - Around 30 minute computation time each.

DNS Validation

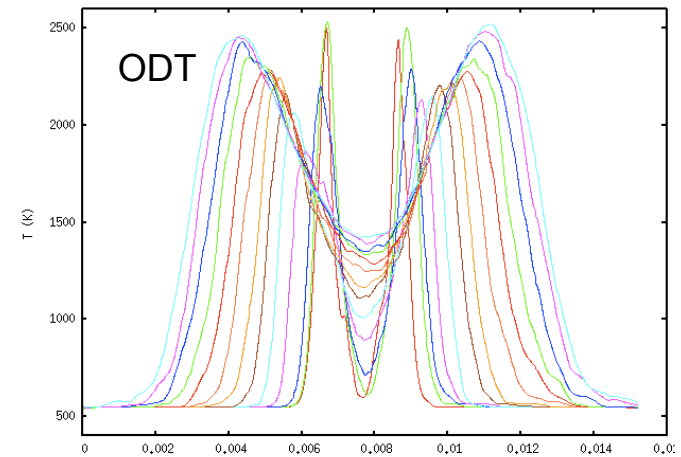
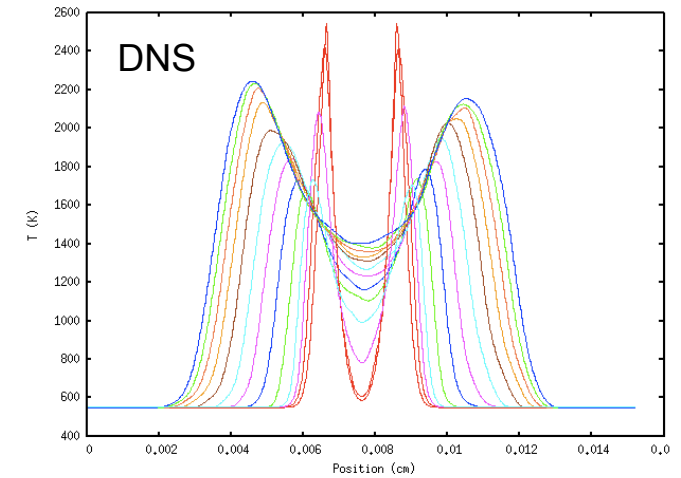
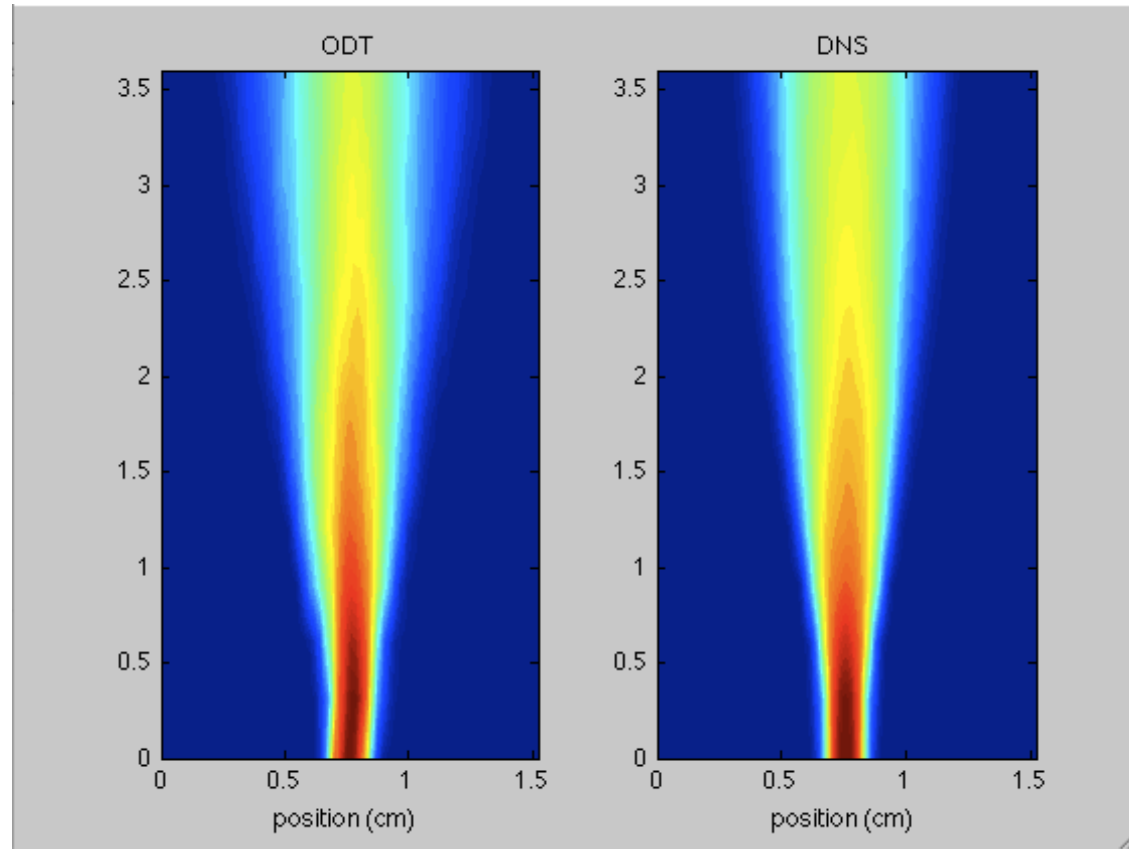
- Compare ODT to temporally-evolving DNS
- Planar ethylene jet
- Extinction, reignition
 - Three cases with varying Da
- Tune the ODT parameters
- Compare means, fluctuations
 - T , mixture fraction, species



ODT / DNS - Jet spread rate



ODT / DNS - Mixture Fraction, Temperature



Conclusions

- ODT is a promising method to examining flame structure
 - Applied successfully to a wide range of problems
 - Computationally affordable
 - Allows many parametric studies
 - Intermittent flame interface
 - Statistics of time temperature histories
 - Capture overall flow characteristics as well as fine structures

